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**Hyper inverse Wishart distribution for non-decomposable
graphs and its application to Bayesian inference for
Gaussian graphical models**

by

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Abstract

While conjugate Bayesian inference in decomposable Gaussian graphical models is largely solved, the non-decomposable case still poses difficulties concerned with the specification of suitable priors and the evaluation of normalising constants. In this paper we derive the DY-conjugate prior (Diaconis and Ylvisaker, 1979) for non-decomposable models and show that it can be regarded as a generalisation to an arbitrary graph G of the hyper inverse Wishart distribution (Dawid and Lauritzen, 1993). In particular, if G is an incomplete prime graph it constitutes a nontrivial generalisation of the inverse Wishart distribution.

Inference based on marginal likelihood requires the evaluation of a normalising constant and we propose an importance sampling algorithm for its computation. Examples of structural learning involving non-decomposable models are given.

In order to deal efficiently with the set of all positive definite matrices with non-decomposable zero-pattern we introduce the operation of triangular completion of an incomplete triangular matrix. Such a device turns out to be extremely useful both in the proof of theoretical results and in the implementation of the Monte Carlo procedure.

Keywords: Cholesky decomposition; Conjugate distribution; Gaussian graphical model; Importance sampling; Hyper inverse Wishart distribution; Matrix completion; Non-decomposable graph; Normalising constant.

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1 Introduction

Bayesian analysis of undirected Gaussian graphical models has been considered in literature mainly for the subclass of models with decomposable graph (Dawid and Lauritzen, 1993; Cowell *et al.*, 1999; Giudici and Green, 1999).

An arbitrary graph G can be successively decomposed into its prime components (P_1, \dots, P_k) . Since the prime components of a decomposable graph G are all complete, the analysis of a graphical model with decomposable graph may be reduced to the analysis of saturated marginal models corresponding to the cliques of G (see Lauritzen, 1996).

The inverse Wishart distribution is conjugate for the parameter Σ of the saturated model and, for the analysis of decomposable Gaussian graphical models, Dawid and Lauritzen (1993) introduced a generalisation of such a distribution and named it hyper inverse Wishart. The characterising features of this distribution are the hyper-Markov property and its clique-marginals that are all inverse Wishart, but Dawid and Lauritzen (1993) also showed that it satisfies the strong hyper-Markov property that allows the local computation of several statistical quantities. Furthermore Bjerg and Nielsen (1993) showed that the hyper inverse Wishart distribution is the DY-conjugate prior for the model (Diaconis and Ylvisaker, 1979).

For a model selection procedure, however, it is natural to choose candidates from the set of all graphs and a restriction to the subset of decomposable models is somewhat artificial. For instance, Cox and Wermuth (1993) noticed that for the variables in Table 1, a non-decomposable graph like that in Figure 1 seems to be strongly indicated (see also Cox and Wermuth, 1996, p.70).

Figure 1 about here

Another example where a chordless four-cycle might well describe the relations between variables is shown in Table 2. These data are reproduced in several texts; for an analysis based on graphical models see Whittaker (1990) and Bjerg and Nielsen (1993).

Tables 1 and 2 about here

This paper is concerned with the Bayesian analysis of Gaussian graphical models with non-decomposable graph G . A central role is played by the incomplete prime components of G . The set of all prime graphs on p vertices includes the complete graph but, if $p \geq 4$, it also includes incomplete graphs; the chordless four-cycle in Figure 1 is the smallest incomplete prime graph (for a discussion on its interpretation see Cox and Wermuth, 2000).

We derive the DY-conjugate prior for an arbitrary graph G and call it a hyper inverse Wishart because it satisfies the strong hyper-Markov property and its marginal distributions corresponding to the complete prime components of G are inverse Wishart. Of interest are the marginal distributions for the incomplete prime components of G that can be regarded as a generalisation of the inverse Wishart distribution to the set of all prime graphs.

A marginal likelihood approach to structural learning requires the evaluation of a normalising constant. We propose an importance sampling procedure for its computation in the case the prior distribution is hyper inverse Wishart. For an efficient implementation of the procedure, a strategy to deal efficiently with the set of all positive definite matrices with non-decomposable zero-pattern is required. We solve this problem by considering the Cholesky decomposition of Σ^{-1} and introducing the operation of triangular completion of an incomplete triangular matrix. This paper rely heavily on this idea that is also used in the proof of theoretical results. Related works on the triangular decomposition of either the covariance matrix or its inverse include Massam and Neher (1997, 1998), Pourahmadi (1999), Roverato (2000), Wermuth (1980) and Wermuth and Cox (1997).

The notation, including the definitions of incomplete triangular matrix and triangular completion, is presented in Section 2. The general theory relating to Gaussian graphical models and the hyper inverse Wishart distribution is presented in Section 3. In Section 4 we derive the DY-conjugate prior for non-decomposable models and investigate its properties. The proposed importance distribution and a discussion on the performance of the Monte Carlo procedure is given in Section 5. Examples of structural learning for the data in Tables 1 and 2 are discussed in Section 6. Finally, in Appendix A we present a detailed description of the technical aspects concerning the triangular completion operation.

2 Notation

Unlike decomposable models, in the non-decomposable case the the analysis of graphical models cannot be reduced to the analysis of saturated marginal models but requires handling non-saturated irreducible models explicitly. To deal with the consequent notational difficulties Roverato and Whittaker (1998) proposed the use of an edge set indexing notation to be applied to Isserlis matrices, incomplete symmetric matrices and matrix completion. In this section we review the main features of such a framework, introduce the graph theory notation used in this paper and extend the idea of incomplete matrix and matrix completion to the set of upper triangular matrices. A full account of graph theory requisite for graphical models can be found in Cowell *et al.* (1996).

2.1 Edge set indexing notation and the Isserlis matrix

Let V be a finite set with $|V| = p$, and let Γ be a $p \times p$ matrix. The rows and columns of Γ are indexed by the elements of V , so that Γ itself is indexed by $V \times V$. If $V = \{1, \dots, p\}$, $\Gamma = \{\gamma_{ij}\}$ is indexed by row and column numbers. When the ordering of the elements of V is fixed, we assume that the rows and columns of Γ are ordered accordingly.

The Isserlis matrix of a positive definite matrix Γ , $\text{Iss}(\Gamma)$, (Isserlis, 1918; Roverato and Whittaker, 1998) is the symmetric matrix indexed by $\mathcal{W} \times \mathcal{W}$ where $\mathcal{W} = \{(i, j) :$

$i, j \in V, i \leq j$ }, with elements $\{\text{Iss}(\Gamma)\}_{(i,j),(r,s)} = \gamma_{ir}\gamma_{js} + \gamma_{is}\gamma_{jr}$. The determinant of the Isserlis matrix is $|\text{Iss}(\Gamma)| = 2^p |\Gamma|^{p+1}$.

We denote an arbitrary undirected graph by $G = (V, \mathcal{V})$, where V is the vertex set and \mathcal{V} is the set of edges. We use the convention that for all $i \in V$ the pair (i, i) is included in the edge set \mathcal{V} and that if $(i, j) \in \mathcal{V}$ then $i \leq j$. The set \mathcal{W} is therefore the edge set of the complete graph and we denote by $\bar{\mathcal{V}} = \mathcal{W} \setminus \mathcal{V}$ the set of edges not in G . Similarly for a nonempty subset A of V the edge set of the induced subgraph G_A is denoted by $\mathcal{A} = \mathcal{V} \cap (A \times A)$, while $\bar{\mathcal{A}} = \bar{\mathcal{V}} \cap (A \times A)$ indicates the set of edges not in G_A .

Example 1. For the graph $G = (V, \mathcal{V})$ in Figure 1, the vertex and edge sets are $V = \{1, 2, 3, 4\}$ and $\mathcal{V} = \{(1, 1), (2, 2), (3, 3), (4, 4), (1, 2), (1, 4), (2, 3), (3, 4)\}$ respectively, while $\bar{\mathcal{V}} = \{(1, 3), (2, 4)\}$. For $A = \{1, 3\}$, $\mathcal{A} = \{(1, 1), (3, 3)\}$ and $\bar{\mathcal{A}} = \{(1, 3)\}$, while for $B = \{1, 2\}$. G_B is complete so that $\mathcal{B} = \{(1, 1), (2, 2), (1, 2)\}$ and $\bar{\mathcal{B}} = \emptyset$. \square

For any undirected graph $G = (V, \mathcal{V})$ the pair $(\mathcal{V}, \bar{\mathcal{V}})$ is a partition of \mathcal{W} . To this correspond the submatrices $\text{Iss}(\Gamma)_{\mathcal{V}\mathcal{V}}$, $\text{Iss}(\Gamma)_{\mathcal{V}\bar{\mathcal{V}}}$ and $\text{Iss}(\Gamma)_{\bar{\mathcal{V}}\bar{\mathcal{V}}}$ as well as the partial matrix $\text{Iss}(\Gamma)_{\mathcal{V}\bar{\mathcal{V}}|\bar{\mathcal{V}}\bar{\mathcal{V}}} = \text{Iss}(\Gamma)_{\mathcal{V}\bar{\mathcal{V}}} - \text{Iss}(\Gamma)_{\mathcal{V}\bar{\mathcal{V}}}\text{Iss}(\Gamma)_{\bar{\mathcal{V}}\bar{\mathcal{V}}}^{-1}\text{Iss}(\Gamma)_{\bar{\mathcal{V}}\bar{\mathcal{V}}}$. The nonempty subsets A and B of V identify the submatrix $\text{Iss}(\Gamma)_{\mathcal{A}\mathcal{B}}$ of $\text{Iss}(\Gamma)_{\mathcal{V}\mathcal{V}}$ through the edge sets of the corresponding induced subgraphs. We recall that the Isserlis matrix can be computed locally: namely $\text{Iss}(\Gamma)_{\mathcal{A}\mathcal{A}} = \text{Iss}(\Gamma_{\mathcal{A}\mathcal{A}})_{\mathcal{A}\mathcal{A}}$ so that for A complete $\text{Iss}(\Gamma)_{\mathcal{A}\mathcal{A}} = \text{Iss}(\Gamma_{\mathcal{A}\mathcal{A}})$ (Roverato and Whittaker, 1998).

Vertices i and j , with $i < j$, are said to be neighbours if $(i, j) \in \mathcal{V}$. The boundary $\text{bd}(A)$ of a subset A of V is the set of vertices in $V \setminus A$ that are neighbours of vertices in A . A graph $G = (V, \mathcal{V})$ is said to be collapsible onto $B \subseteq V$ if every connected component of $V \setminus B$ has complete boundary in G .

We denote by P_1, \dots, P_k the prime components of an undirected graph $G = (V, \mathcal{V})$. A prime component is a subset of V that induces a, possibly incomplete, maximal subgraph without a complete separator. Any non-decomposable graph has at least one incomplete prime component. Efficient algorithms have been developed to find all prime components of any undirected graph (Leimer, 1993).

The prime components of an undirected graph can be ordered to form a perfect sequence (P_1, \dots, P_k) of subsets of V and, following standard notation, we denote by $H_j = P_1 \cup \dots \cup P_j$ the histories, by $R_j = P_j \setminus H_{j-1}$ the residuals and by $S_j = H_{j-1} \cap P_j$ the separators of the sequence. Recall that, for all $j = 2, \dots, k$ the subgraph G_{H_j} is collapsible onto $G_{H_{j-1}}$ (Lauritzen, 1996, Lemma 2.11). If the vertices V are enumerated by taking first the vertices in R_k , then those in R_{k-1}, \dots, R_2, P_1 , we say that the vertices are enumerated along a perfect sequence of prime components of G .

Assume now the vertex ordering $V = \{1, 2, \dots, p\}$ fixed and, for $i = 1, \dots, p$, let $\{i\} = \{1, \dots, i\}$ and $\langle i \rangle = \{i + 1, \dots, p\}$ so that $\{p\} = V$ and $\langle p \rangle = \emptyset$. We denote by $\nu_i = |\text{bd}(i) \cap \langle i \rangle|$ the number of vertices adjacent to i following i in the given ordering.

We remark that for a decomposable graph $G = (V, \mathcal{V})$ a perfect sequence of prime components of G is a perfect sequence (C_1, \dots, C_k) of cliques of G . In this

case, if the vertices V are enumerated along a perfect sequence (C_1, \dots, C_k) then the vertex ordering is said to follow a perfect vertex elimination scheme for G and the sets $\text{bd}(i) \cap \langle i \rangle$ are complete for all $i = 1, \dots, p-1$. We also recall that, a perfect vertex elimination scheme taken in reverse order forms a perfect numbering of the vertices of G (Lauritzen, 1996, Lemma 2.12).

2.2 Incomplete matrices and matrix completion

Let M^+ denote the set of all $|V| \times |V|$ positive definite matrices. For a set $\mathcal{C} \subseteq \mathcal{W}$ the \mathcal{C} -incomplete symmetric matrix $\Gamma^{\mathcal{C}}$ is defined as the symmetrised matrix indexed by $V \times V$ with elements $\{\gamma_{ij}\}$ for all $(i, j) \in \mathcal{C}$, and with the remaining elements unspecified.

Example 2. For the graph $G = (V, \mathcal{V})$ in Figure 1, the \mathcal{V} -incomplete symmetric matrix and its submatrix induced by $A = \{1, 3\}$ are respectively

$$\Gamma^{\mathcal{V}} = \begin{pmatrix} \gamma_{11} & \gamma_{12} & * & \gamma_{14} \\ \gamma_{21} & \gamma_{22} & \gamma_{23} & * \\ * & \gamma_{32} & \gamma_{33} & \gamma_{34} \\ \gamma_{41} & * & \gamma_{43} & \gamma_{44} \end{pmatrix} \quad \text{and} \quad \Gamma_{AA}^{\mathcal{V}} = \Gamma_{AA}^A = \begin{pmatrix} \gamma_{11} & * \\ * & \gamma_{33} \end{pmatrix},$$

where asterisks denote unspecified elements. □

If it is possible to fill an incomplete symmetric matrix $\Gamma^{\mathcal{C}}$ to obtain a (full) positive definite matrix we say that $\Gamma^{\mathcal{C}}$ admits a positive completion. For an undirected graph $G = (V, \mathcal{V})$, we denote by $M_*^+(G)$ the set of all \mathcal{V} -incomplete symmetric matrices $\Gamma^{\mathcal{V}}$ that admit positive completion and by $M^+(G)$ the subset of all positive definite matrices Γ^{-1} satisfying $\{\Gamma^{-1}\}_{ij} = 0$ whenever $(i, j) \in \bar{\mathcal{V}}$.

We say that Γ is the *PD-completion* of $\Gamma^{\mathcal{V}} \in M_*^+(G)$ if it is the unique positive definite matrix such that

$$(\Gamma)^{\mathcal{V}} = \Gamma^{\mathcal{V}} \quad \text{and} \quad \Gamma^{-1} \in M^+(G). \quad (1)$$

See Grone *et al.* (1984) for a proof of the existence and uniqueness of such matrix.

The properties of *PD-completed* matrices and their Isserlis matrices can be found in Lauritzen (1996) and Roverato and Whittaker (1998) respectively. Here we recall some of them.

If $\Gamma^{-1} \in M^+(G)$ where G is an undirected graph with prime components (P_1, \dots, P_k) , then

$$|\Gamma| = \frac{\prod_{j=1}^k |\Gamma_{P_j P_j}|}{\prod_{j=2}^k |\Gamma_{S_j S_j}|} \quad \text{and} \quad |\text{Iss}(\Gamma)_{\mathcal{V}\mathcal{V}}| = \frac{\prod_{j=1}^k |\text{Iss}(\Gamma_{P_j P_j})_{\mathcal{P}_j \mathcal{P}_j}|}{\prod_{j=2}^k |\text{Iss}(\Gamma_{S_j S_j})|} \quad (2)$$

where if P_j is complete $|\text{Iss}(\Gamma_{P_j P_j})_{\mathcal{P}_j \mathcal{P}_j}| = |\text{Iss}(\Gamma_{P_j P_j})| = 2^{|P_j|} |\Gamma_{P_j P_j}|^{|P_j|+1}$. Furthermore

$$\Gamma^{-1} = \sum_{j=1}^k [\Gamma_{P_j P_j}^{-1}]^0 - \sum_{j=2}^k [\Gamma_{S_j S_j}^{-1}]^0, \quad (3)$$

where $[\Gamma_{PP}]^0$ denotes the $|V| \times |V|$ matrix obtained by padding zero entries around Γ_{PP} to obtain full dimension. We remark that a relation similar to (3) also holds for $\text{Iss}(\Gamma)_{\mathcal{V}\mathcal{V}}$ (Roverato and Whittaker, 1998 equation (14)) but it is not required here.

When G is decomposable, equation (3) can be used to compute the PD -completion of $\Gamma^{\mathcal{V}} \in M_*^+(G)$, but in the non-decomposable case PD -completion operations are performed by means of iterative procedures, typically the standard iterative proportional fitting algorithm (see Whittaker, 1990, p.182).

We consider now the set $M^{\mathfrak{q}}$ of all $|V| \times |V|$ upper triangular matrices with positive diagonal and, in parallel with symmetric incomplete matrices and positive definite completion, we define triangular incomplete matrices and introduce the concept of triangular completion.

For a set $\mathcal{C} \subseteq \mathcal{W}$ we define the \mathcal{C} -incomplete triangular matrix $\Phi^{\mathcal{C}}$ as the upper triangular matrix indexed by $V \times V$ with elements $\{\phi_{ij}\}$ for all $(i, j) \in \mathcal{C}$, and with the remaining elements unspecified.

Example 3. For the graph $G = (V, \mathcal{V})$ in Figure 1, the \mathcal{V} -incomplete triangular matrix and its submatrix induced by $A = \{1, 3\}$ are respectively

$$\Phi^{\mathcal{V}} = \begin{pmatrix} \phi_{11} & \phi_{12} & * & \phi_{14} \\ 0 & \phi_{22} & \phi_{23} & * \\ 0 & 0 & \phi_{33} & \phi_{34} \\ 0 & 0 & 0 & \phi_{44} \end{pmatrix} \quad \text{and} \quad \Phi_{AA}^{\mathcal{V}} = \Phi_{AA}^{\mathcal{A}} = \begin{pmatrix} \phi_{11} & * \\ 0 & \phi_{33} \end{pmatrix}.$$

□

We denote by $M_*^{\mathfrak{q}}(G)$ the set of all \mathcal{V} -incomplete triangular matrices with positive diagonal. It is straightforward to see that any completion Φ of $\Phi^{\mathcal{V}} \in M_*^{\mathfrak{q}}(G)$ satisfies the relation $\Phi^{\top} \Phi \in M^+$.

The factorisation $\Gamma^{-1} = \Phi^{\top} \Phi$ with $\Gamma^{-1} \in M^+$ and $\Phi \in M^{\mathfrak{q}}$ is called the Cholesky decomposition of Γ^{-1} and defines a bijective mapping from M^+ to $M^{\mathfrak{q}}$; $\pi : M^+ \rightarrow M^{\mathfrak{q}}$. For an undirected graph $G = (V, \mathcal{V})$, the mapping $\pi(\cdot)$ identifies the subset $M^{\mathfrak{q}}(G) = \pi\{M^+(G)\}$ of all $\Phi \in M^{\mathfrak{q}}$ such that $\Phi^{\top} \Phi \in M^+(G)$. We say that Φ is the T -completion of $\Phi^{\mathcal{V}} \in M_*^{\mathfrak{q}}(G)$ if it is the unique upper triangular matrix such that

$$(\Phi)^{\mathcal{V}} = \Phi^{\mathcal{V}} \quad \text{and} \quad \Phi \in M^{\mathfrak{q}}(G). \quad (4)$$

The technical aspects concerning the T -completion of an incomplete triangular matrix, including its existence and uniqueness, are given in Appendix A. In particular we show that for all $\Phi^{\mathcal{V}} \in M_*^{\mathfrak{q}}(G)$ the T -completion Φ can be computed efficiently in closed form. In fact, in T -completion a large amount of local and parallel computations are possible. Firstly, the unspecified elements on the same row of $\Phi^{\mathcal{V}}$ can be computed in parallel. Secondly, if the vertices V are enumerated along a perfect sequence of prime components (P_1, \dots, P_k) of G , then the T -completion of $\Phi^{\mathcal{V}}$ only involves the \mathcal{P}_j -incomplete triangular submatrices $\Phi_{\mathcal{P}_j \mathcal{P}_j}^{\mathcal{P}_j}$ corresponding to the incomplete prime components of G . These may be completed locally with respect to $G_{\mathcal{P}_j}$ and in parallel (see Theorem 1).

Throughout this paper, for an undirected graph $G = (V, \mathcal{V})$, we always consider the vertices V enumerated along a perfect sequence of prime components of G and write $\Gamma^{-1} = \Phi^\top \Phi$ to define the Cholesky decomposition of Γ^{-1} .

Both *PD*- and *T*-completion are computational devices for the generation of elements from the set $M^+(G)$. In Gaussian graphical models $M^+(G)$ represents the canonical parameter space and (1) can be reformulated as the equations satisfied by the maximum likelihood estimate $\hat{\Sigma}$ of the covariance matrix Σ (Speed and Kiiveri, 1986). However, when G is non-decomposable it cannot be performed efficiently and this proscribes its use in Bayesian computational intensive procedures where an efficient exploration of the parameter space $M^+(G)$ is required. *T*-completion cannot be applied to the computation of maximum likelihood estimates but turns out to be very useful in Bayesian applications.

3 Hyper inverse Wishart distribution

In this section we define Gaussian graphical models and present the theory related to conjugate priors, hyper-Markov properties and hyper-inverse Wishart distributions required in this paper. We refer to Lauritzen (1996) for a full account of Gaussian graphical model theory and to Dawid and Lauritzen (1993) for the theory of hyper-Markov distributions. For a definition of standard and DY-conjugate families and a review of their properties see Gutiérrez-Peña and Simth (1997).

Let $X \equiv X_V$ be a $|V|$ -variate Normal random vector with mean equal to zero and covariance matrix $\Sigma = \{\sigma_{ij}\}$. The covariance selection model, or Gaussian graphical model, for X with graph $G = (V, \mathcal{V})$ is specified by assuming that $K = \Sigma^{-1}$ belongs to $M^+(G)$ (Dempster, 1972; Wermuth, 1976). A model whose graph is decomposable is itself called decomposable. For a subset $B \subset V$, the submatrix Σ_{BB} is the parameter of the marginal distribution of X_B and, if $A = V \setminus B$,

$$\Sigma_{A|B} = \Sigma_{AA} - \Sigma_{AB} \Sigma_{BB}^{-1} \Sigma_{BA} \quad \text{and} \quad \Gamma_{A|B} = \Sigma_{AB} \Sigma_{BB}^{-1}$$

are the parameters relative to the conditional distribution of X_A given X_B or, more compactly, of $X_A|X_B$.

The Gaussian graphical model is a regular exponential family (Lauritzen, 1996, p.132). In the saturated case G is the complete graph and the DY-conjugate prior, that is the distribution induced on the moment parameter Σ by the standard conjugate prior for the canonical parameter $K = \{\kappa_{ij}\}$ (Diaconis and Ylvisaker, 1979), has an inverse Wishart distribution. Using the parameterisation of Dawid (1981), we write $\Sigma \sim IW(\delta, D)$ with density

$$f_V(\Sigma | \delta, D) = h_V(\delta) \frac{|\Sigma|^{-(\delta+2|V|)/2}}{|D|^{-(\delta+|V|-1)/2}} \exp \left\{ -\frac{1}{2} \text{tr}(\Sigma^{-1} D) \right\},$$

where

$$h_V(\delta) = \frac{2^{-|V|(\delta+|V|-1)/2}}{\Gamma_{|V|} \left\{ \frac{1}{2}(\delta + |V| - 1) \right\}} \quad (5)$$

is the normalising constant (Muirhead, 1982, p.113). The standard conjugate prior for the model has therefore a Wishart distribution, $K \sim W(\delta + |V| - 1, Q)$, where $\delta > 0$ and $D = Q^{-1}$ is a positive definite matrix. We recall that the multivariate Gamma function has form $\Gamma_{|V|}(y) = \pi^{|V|(|V|-1)/4} \prod_{i=1}^{|V|} \Gamma\{y - (i-1)/2\}$.

If $G = (V, \mathcal{V})$ is an arbitrary undirected graph, the standard conjugate prior for K can be obtained from the saturated case by conditioning on the event $\{K \in M^+(G)\}$. Such a distribution was introduced by Bjerg and Nielsen (1993) who named it Markov Wishart (see also Giudici, 1996); here, following Roverato (2000) we call it a G -conditional Wishart and write $K \sim W_G(\delta + |V| - 1, Q)$ with density

$$q_G(K | \delta, Q) \propto |K|^{(\delta-2)/2} \exp\left\{-\frac{1}{2} \text{tr}(KQ^{-1})\right\}, \quad K \in M^+(G). \quad (6)$$

We remark that the matrix hyperparameter of the distribution is an incomplete matrix $D^\mathcal{V} \in M^+(G)$. This can be seen by recalling that $\text{tr}(KD) = \sum_{i=1}^p \sum_{j=1}^p \kappa_{ij} d_{ij}$ so that, since $\kappa_{ij} = 0$ for all $(i, j) \in \bar{\mathcal{V}}$, only the specified elements of $D^\mathcal{V}$ enter into the specification of the density. For this reason, in the following we can assume without loss of generality that D is a PD -completed matrix and that $Q \in M^+(G)$.

Bjerg and Nielsen (1993) showed that, in the decomposable case, the DY-conjugate prior for $\Sigma^\mathcal{V}$ is hyper inverse Wishart, $\Sigma^\mathcal{V} \sim HIW_G(\delta, D^\mathcal{V})$ (see also Roverato, 2000). The hyper inverse Wishart distribution was first introduced by Dawid and Lauritzen (1993) who defined it as the unique hyper-Markov distribution for $\Sigma^\mathcal{V}$ with marginals $\Sigma_{P_j P_j} \sim IW(\delta, D_{P_j P_j})$, for all $j = 1, \dots, k$. Recall that, in the decomposable case for all $j = 1, \dots, k$ the submatrices $\Sigma_{P_j P_j}$ of $\Sigma^\mathcal{V}$ are fully specified. The hyper inverse Wishart distribution can be obtained as hyper-Markov combination of the marginal inverse Wishart distributions for the prime components of G so that its density factorises as

$$f_G(\Sigma^\mathcal{V} | \delta, D^\mathcal{V}) = \frac{\prod_{j=1}^k f_{P_j}(\Sigma_{P_j P_j} | \delta, D_{P_j P_j})}{\prod_{j=2}^k f_{S_j}(\Sigma_{S_j S_j} | \delta, D_{S_j S_j})}. \quad (7)$$

We now mention some properties of the hyper inverse Wishart distribution. For a decomposable graph $G = (V, \mathcal{V})$ assume $\Sigma^\mathcal{V} \sim HIW_G(\delta, D^\mathcal{V})$ and let $K = \Sigma^{-1}$ where Σ is the PD -completion of $\Sigma^\mathcal{V}$. Then, for every pair of subsets B and $A = V \setminus B$ of V such that G is collapsible onto B ,

R.1 $\Sigma_{BB}^B \sim HIW_{G_B}(\delta, D_{BB}^B)$, or equivalently $\Sigma_{BB}^{-1} = K_{BB|A} \sim W_{G_B}(\delta + |B| - 1, Q_{BB|A})$;

R.2 Σ_{BB} is independent of $(\Sigma_{AA|B}, \Gamma_{A|B})$; shortly $\Sigma_{BB} \perp\!\!\!\perp (\Sigma_{AA|B}, \Gamma_{A|B})$. Equivalently $K_{BB|A} \perp\!\!\!\perp (K_{AA}, K_{AB})$.

Result *R.1* derives from the constructing procedure of the hyper inverse Wishart distribution. Property *R.2* gives, in an alternative formulation, the strong hyper-Markov property for the distribution of $\Sigma^\mathcal{V}$ (Dawid and Lauritzen, 1993, Proposition 3.18). This plays an important role in Bayesian inference because it allows the local

computation of important statistical quantities with a consequent simplification of the inference process.

The upper triangular matrix Φ defined by $K = \Phi^\top \Phi$ constitutes a useful reparameterisation of the model into variation independent terms (see also Consonni and Veronese, 2000). For the distribution induced by Σ^ν on Φ the following results are available.

R.3 For every ordering of the vertices V such that $B = \{b, b+1, \dots, p\}$ the first $|A|$ rows of Φ are independent of the remaining $|B|$ rows; that is $(\Phi_{AA}, \Phi_{AB}) \perp\!\!\!\perp \Phi_{BB}$.

Assume now the vertices V enumerated along a perfect sequence of prime components (P_1, \dots, P_k) of G . Then

R.4 Φ is made up of zeros but for the row-blocks

$$\Phi_{P_1 P_1}, \quad (\Phi_{R_2 R_2} \Phi_{R_2 S_2}), \dots, (\Phi_{R_k R_k} \Phi_{R_k S_k});$$

R.5 the row-block submatrices in *R.4* are mutually independent;

R.6 the rows of every row-block submatrix in *R.4* are mutually independent;

R.7 the distribution of the r th row of Φ can be computed locally as follows. The r th row of Φ belongs to one and only one of the row-blocks in *R.4*. To this corresponds one of the prime components, say P , of G . Thus the r th row of Φ is the i th row of Φ_{PP} and can be partitioned into a zero lower-triangular part, a diagonal element ϕ_{ii} and an upper-triangular part $\phi_{\langle i \rangle} := \phi_{i, \langle i \rangle}^\top \equiv (\phi_{i, i+1}, \dots, \phi_{i, |P|})^\top$. Then, if $T = \{t_{ij}\}$ is defined by $D_{PP}^{-1} = T^\top T$

$$\phi_{ii} \sim t_{ii} \sqrt{\chi_{\delta + \nu_i}^2} \quad \text{and} \quad \phi_{\langle i \rangle} | \phi_{ii} \sim N(\phi_{ii} t_{\langle i \rangle}, T_{\langle i \rangle \langle i \rangle}^\top T_{\langle i \rangle \langle i \rangle}),$$

where χ^2 denotes a chi-squared random variable and $t_{\langle i \rangle} := (t_{i, i+1}, \dots, t_{i, |P|})^\top$. We remark that here both the set $\langle i \rangle$ and the index ν_i are considered with respect to G_P .

Result *R.3* is equivalent to *R.2* by (A10). Result *R.4* was shown by Wermuth (1980); see also Proposition 1 in Appendix A. A proof of properties *R.5* and *R.6* can be found in Massam and Neher (1997); see also Roverato (2000). *R.7* can be derived by applying standard results of the Wishart distribution (see Muirhead, 1982, Theorem 3.2.10) because by (A8) and (A9) the i th row of Φ_{PP} can be obtained by the Cholesky decomposition of $\Sigma_{PP}^{-1} \sim W(\delta - |P| - 1, D_{PP}^{-1})$.

When $G = (V, \mathcal{V})$ is complete, the distribution of Σ is inverse Wishart and results *R1-R7* can be applied by recalling that the complete graph has only one prime component V , its vertices are always enumerated along such a prime component and that it is collapsible onto every $B \subseteq V$.

4 DY-conjugate prior for non-decomposable models

Introducing the hyper inverse Wishart distribution as the DY-conjugate prior for the Gaussian graphical model with decomposable graph G provides a natural way to generalise such a distribution to the non-decomposable case. Here we derive the DY-conjugate prior for a Gaussian graphical model with arbitrary undirected graph $G = (V, \mathcal{V})$ and consider the extension to the non-decomposable case of its properties. An interesting feature of this distribution is that when G is an incomplete prime graph, it can be regarded as a nontrivial generalisation of the inverse Wishart distribution. Otherwise it can be obtained by hyper-Markov combination of the DY-conjugate priors for the prime components of G .

Let $G = (V, \mathcal{V})$ be an arbitrary undirected graph. By definition, the DY-conjugate prior for the Gaussian graphical model with graph G is computed from the standard conjugate prior $K \sim W_G(\delta + |V| - 1, Q)$ via the change of variables to $\Sigma = K^{-1}$; that is, the transformation between the nonzero entries of K and the specified entries of $\Sigma^\mathcal{V}$. The Jacobian of this transformation is $|J(K \rightarrow \Sigma^\mathcal{V})| = 2^{-p} |\text{Iss}(\Sigma^{-1})_{\mathcal{V}\mathcal{V}}| = 2^p |\text{Iss}(\Sigma)_{\mathcal{V}\mathcal{V}}|^{-1}$ (Roverato and Whittaker, 1998, equations (10) and (11)) so that the resulting density function for $\Sigma^\mathcal{V} \in M_\star^+(G)$ has form

$$f_G(\Sigma^\mathcal{V} | \delta, D^\mathcal{V}) = h_G(\delta, D^\mathcal{V}) 2^{\frac{p}{2}} |\text{Iss}(D)_{\mathcal{V}\mathcal{V}}|^{\frac{1}{2}} \times |\text{Iss}(\Sigma)_{\mathcal{V}\mathcal{V}}|^{-1} \frac{|\Sigma|^{-(\delta-2)/2}}{|D|^{-(\delta-2)/2}} \exp \left\{ -\frac{1}{2} \text{tr}(\Sigma^{-1}D) \right\} \quad (8)$$

where Σ and D are the PD -completions of $\Sigma^\mathcal{V}$ and $D^\mathcal{V} \in M_\star^+(G)$ respectively. It should be noticed that some terms in (8) do not depend on $\Sigma^\mathcal{V}$ and could therefore be included into the normalising constant $h_G(\delta, D^\mathcal{V})$. However, in this way, when G is complete $h_G(\delta, D^\mathcal{V}) = h_V(\delta)$ in (5). More generally, when G is decomposable, the normalising constant does not depend on $D^\mathcal{V}$, $h_G(\delta, D^\mathcal{V}) = h_G(\delta)$, and can be computed by (5) and (7); see also Roverato (2000, Proposition 2). In the non-decomposable case the normalising constant is not known and the next section is concerned with its numerical evaluation.

If (P_1, \dots, P_k) is a perfect sequence of prime components of G , then the density (8) can be factorised as

$$f_G(\Sigma^\mathcal{V} | \delta, D^\mathcal{V}) = \frac{\prod_{j=1}^k f_{G_{P_j}}(\Sigma_{P_j P_j}^{\mathcal{P}_j} | \delta, D_{P_j P_j}^{\mathcal{P}_j})}{\prod_{j=2}^k f_{G_{S_j}}(\Sigma_{S_j S_j} | \delta, D_{S_j S_j})} \quad (9)$$

that generalises (7). This factorisation can be shown by applying (2) to both $|\text{Iss}(D)_{\mathcal{V}\mathcal{V}}|$ and $|\text{Iss}(\Sigma)_{\mathcal{V}\mathcal{V}}|$ and by using (3) to decompose Σ^{-1} in the trace. Equation (9) shows that the DY-conjugate prior can be constructed by hyper-Markov combination of the DY-conjugate priors for the prime components of the graph that, when complete, have inverse Wishart distribution. For this reason, for an arbitrary graph $G = (V, \mathcal{V})$,

we write $\Sigma^\mathcal{V} \sim HIW_G(\delta, D^\mathcal{V})$ to say that the distribution of $\Sigma^\mathcal{V}$ has density (8), extending in this way the notation of Dawid and Lauritzen (1993).

We now consider results *R.1-R.7* given in Section 3 for the decomposable case and show that *R.1-R.5* hold for an arbitrary graph G . We first give the main result with respect to the G -conditional Wishart distribution and then derive its implications for the hyper inverse Wishart distribution.

Lemma 1 *Suppose $K \sim W_G(\delta + |V| - 1, Q)$, where $G = (V, \mathcal{V})$ is an arbitrary undirected graph. For every pair of subsets $B \subseteq V$ and $A = V \setminus B$ of V such that G is collapsible onto B*

$$(i) K_{BB|A} \sim W_{G_B}(\delta + |B| - 1, Q_{BB|A});$$

$$(ii) K_{BB|A} \perp\!\!\!\perp (K_{AA}, K_{AB});$$

(iii) *for every ordering of the vertices V such that $B = \{b, b+1, \dots, p\}$ it holds that $(\Phi_{AA}, \Phi_{AB}) \perp\!\!\!\perp \Phi_{BB}$ where Φ is defined by $K = \Phi^\top \Phi$.*

Proof. See Appendix B. □

As an immediate consequence of Lemma 1 we obtain the generalisation to an arbitrary graph G of results *R.1* and *R.2*.

Corollary 1 *Let $G = (V, \mathcal{V})$ an arbitrary undirected graph and $\Sigma^\mathcal{V} \sim HIW_G(\delta, D^\mathcal{V})$. Whenever G is collapsible onto $B \subseteq V$*

$$(i) \Sigma_{BB}^B \sim HIW_{G_B}(\delta, D_{BB}^B);$$

$$(ii) (\Gamma_{A|B}, \Sigma_{AA|B}) \perp\!\!\!\perp \Sigma_{BB};$$

where $A = V \setminus B$.

An undirected graph G is collapsible onto any complete subset of V , and in this case result (i) of Corollary 1 can be reformulated as follows.

Corollary 2 *Let $G = (V, \mathcal{V})$ an arbitrary undirected graph and $\Sigma^\mathcal{V} \sim HIW_G(\delta, D^\mathcal{V})$. For every complete subset $C \subseteq V$, $\Sigma_{CC} \sim IW(\delta, D_{CC})$.*

Note that Corollary 1 (ii) can be considered as an extension to the non-decomposable case of the strong hyper-Markov property of Σ . In particular, Corollary 1 makes clear that, as well as for the decomposable case, also in our more general formulation the hyper inverse Wishart distribution is characterised by the strong hyper-Markov property and its prime-component marginal distributions. However, in this case it is important to make a distinction between complete and incomplete prime components of G . For every complete prime component C of G the submatrix Σ_{CC} has an inverse Wishart distribution whereas the distribution of Σ_{PP}^P , where P is an incomplete prime component, is $HIW_{G_P}(\delta, D_{PP}^P)$ and cannot be further simplified. In fact, the hyper inverse Wishart distribution for incomplete prime graphs is a truly novel distribution.

Interestingly, it shares the relevant properties of the inverse Wishart distribution: by Corollary 2 all its clique-marginals have inverse Wishart distribution and, by Corollary 1, it satisfies *R.2*. Such a property plays a key role in this context: Dawid and Lauritzen (1993, Proposition 3.16) showed that, in the decomposable case, a necessary and sufficient condition for a hyper-Markov distribution for $\Sigma^\mathcal{V}$ to be strong hyper-Markov is that all the prime-component marginal distributions of $\Sigma^\mathcal{V}$ satisfy *R.2*. Furthermore, Geiger and Heckerman (1999) showed that, for G complete and $|V| > 2$, *R.2* characterises the inverse Wishart distribution.

Example 4. Let $\Sigma^\mathcal{V} \sim HIW_G(\delta, D^\mathcal{V})$ where $G = (V, \mathcal{V})$ is the incomplete prime graph in Figure 1. G is collapsible onto every subset $\{i, j\}$ such that $(i, j) \in \mathcal{V}$. Hence, for every $(i, j) \in \mathcal{V}$ with $i \neq j$, the parameter of $X_{\{i,j\}}, \Sigma_{\{i,j\}\{i,j\}}$, has inverse Wishart distribution and is independent of the parameter of $X_{V \setminus \{i,j\}} | X_{\{i,j\}}$. In other words, the distribution of $\Sigma^\mathcal{V}$ is made up of four inverse Wishart marginals combined together so as that the resulting joint distribution satisfy four independence properties; we conjecture that these elements characterise the distribution. \square

We now consider properties *R.3* to *R.7*. These concern the distribution of Φ and are useful in stochastic simulation to deal efficiently with the hyper inverse Wishart distribution. The generalisation to the non-decomposable case of *R.3* is given in Lemma 1 (iii) (for a connection between row-blocks of $\Phi^\mathcal{V}$ and the parameters of the distributions of X_B and $X_A | X_B$ see Corollary 3 in Appendix A). *R.4* derives from Proposition (1) and is shown in Appendix A. That *R.5* holds in the non-decomposable case can be seen by recursively applying Lemma 1 (iii) with $A = R_j$ and $B = H_{j-1}$ for $j = k, \dots, 2$. Properties *R.6* and *R.7* do not hold in general. They are clearly true for the row-block submatrices corresponding to the complete prime components of G but it is not obvious how they can be generalised to an incomplete prime components, say P , of G because in this case $\Phi_{PP} \neq \Phi_{PP}^P$.

5 Computing the normalising constant

The normalising constant of the hyper inverse Wishart distribution is required for the computation of important statistical quantities. However, it is known in closed form only when G is decomposable and its computation by direct Monte Carlo integration is not possible because a procedure for sampling from $\Sigma^\mathcal{V} \sim HIW_G(\delta, D^\mathcal{V})$, when $G = (V, \mathcal{V})$ is non-decomposable, is not available. In this section we propose an importance sampler for the numerical evaluation of $h_G(\delta, D^\mathcal{V})$. In the simulation we carried out the normalising constant seemed not to depend on $D^\mathcal{V}$.

5.1 Importance sampler

Importance sampling evaluates a constant $C = \int g(y) dy$ by drawing N samples $\{y_1, \dots, y_N\}$ from an importance distribution with density $I(y)$ and computing $\hat{C} = N^{-1} \sum_{i=1}^N \frac{g(y_i)}{I(y_i)}$; for instance see Tanner (1996, p.54). The difficulties related to the

implementation of this algorithm to our problem are twofold. First, to deal directly with $\Sigma^\mathcal{V}$ is inefficient because the evaluation of $f_G(\cdot)$ in (8) at a given point $\Sigma^\mathcal{V}$ requires the PD -completion of $\Sigma^\mathcal{V}$. Secondly, the shape of the required distribution over its support needs to be closely tracked by the sampler as the high dimensional spaces quickly lead to numerical inaccuracy.

We solve the first problem by implementing the algorithm with respect to the distribution induced by $\Sigma^\mathcal{V} \sim HIW_G(\delta, D^\mathcal{V})$ on $\Phi^\mathcal{V}$. The advantage is that, the evaluation of the density $g_G(\cdot)$ of $\Phi^\mathcal{V}$ only requires an efficient T -completion operation. We recall that the distribution of $\Phi^\mathcal{V}$, for an arbitrary graph $G = (V, \mathcal{V})$, can be derived from that of a Wishart distribution by the following Condition-Reparameterise (hereafter shortly C-R) procedure:

C-R PROCEDURE

1. For the complete graph (V, \mathcal{W}) assume $K \sim W(\delta + |V| - 1, Q)$;
- 2a. for $G = (V, \mathcal{V})$ condition K on the event $\{K \in M^+(G)\}$ so that $K \sim W_G(\delta + |V| - 1, Q)$;
- 3a. perform the change of variables to $K \rightarrow \Phi^\mathcal{V}$. (The density $g_G(\cdot)$ of $\Phi^\mathcal{V}$ is obtained by replacing K by $\Phi^\mathcal{V} \Phi^\mathcal{V}^\top$ in (6) and multiplying it by the Jacobian in Proposition 3).

As a solution to the second problem, we propose an importance distribution motivated by a constructing procedure characterised, as well as for the C-R procedure above, by one conditioning and one reparameterising step:

R-C PROCEDURE

1. For the complete graph (V, \mathcal{W}) assume $K \sim W(\delta + |V| - 1, Q)$;
- 2b. perform the change of variables to $K \rightarrow \Phi^\mathcal{W}$ (the distribution of $\Phi^\mathcal{W}$ is given in R.5-R.7):
- 3b. for $G = (V, \mathcal{V})$, $I_G(\cdot)$ is the density of $\Phi^\mathcal{V}$ obtained by conditioning $\Phi^\mathcal{W}$ on the event $\{\Phi^\mathcal{W} \in M^+(G)\}$.

Hence, the C-R and the R-C procedures start from a common distribution and perform on this the same operations but in reverse order. The resulting densities $g_G(\cdot)$ and $I_G(\cdot)$ are in general different and, unlike the required distribution $g_G(\cdot)$, it is possible to sample efficiently from the importance distribution by exploiting the recursive computation of T -completion jointly with the independence of the rows of $\Phi^\mathcal{W}$. In fact, conditioning $\Phi^\mathcal{W}$ to be the T -completion of $\Phi^\mathcal{V}$ means to partition $\Phi^\mathcal{W}$ into $(\Phi^\mathcal{V}, \Phi^{\mathcal{W} \setminus \mathcal{V}})$ and to compute the conditional distribution of $\Phi^\mathcal{V} | \Phi^{\mathcal{W} \setminus \mathcal{V}}$. As well as for T -completion, this conditioning operation can be performed recursively by taking the rows of $\Phi^\mathcal{W}$ one at a time, from top to bottom, and a random sample can be efficiently drawn in the same way. This can be seen by writing the density of $\Phi^\mathcal{W}$

as the product of the marginal densities of its rows, and then by further factorising the density of any row of $\Phi^{\mathcal{W}}$ with respect to its diagonal and off-diagonal part as in R.7. Consequently, for $i = 1, \dots, p$, the i th row of $\Phi^{\mathcal{V}}|\Phi^{\mathcal{W}\setminus\mathcal{V}}$ is made up of a diagonal element ϕ_{ii} , that has the same distribution as the corresponding entry of $\Phi^{\mathcal{W}}$, and of an off-diagonal part whose conditional distribution, given ϕ_{ii} , is multivariate normal since it can be obtained from the corresponding conditional distribution of the i th row of $\Phi^{\mathcal{W}}$ by further conditioning $\Phi_{\{i\}\{p\}}$ to be equal to $\Phi_{\{i\}\{p\}}^{\mathcal{V}}(\Phi_{\{i\}\{p\}}^{\mathcal{V}})$ in (A4).

The rate of convergence of the importance sampling procedure depends on how closely $I_G(\cdot)$ mimics $g_G(\cdot)$. On the basis of our experience, the performance of the procedure can be improved by modifying the basic R-C procedure in two ways.

The efficiency of the procedure seems to be related to the dimension $|\mathcal{W}\setminus\mathcal{V}|$ of the conditioning set. For this reason we reformulate the first step of the two procedures so as to allow the dimension of the initial distribution to be closer to that of the final one.

1. Assume $K \sim W_{G^*}(\delta + |V| - 1, Q)$ where $G^* = (V, \mathcal{V}^*)$ is a decomposable graph such that $\mathcal{V} \subseteq \mathcal{V}^*$ and enumerate the vertices V along a perfect sequence of prime components of G^* .

This generalisation has no effect on the distribution resulting from the C-R procedure but it leads to different importance distributions depending on G^* . Nevertheless, the recursive procedure to derive the importance density remains unchanged and can be applied exactly as described above by simply replacing \mathcal{W} by \mathcal{V}^* everywhere.

The properties of the importance distribution depend on the choice of G^* . For instance, if G^* is the fill-in decomposable graph described in Appendix A, then the importance distribution differ from $g_G(\cdot)$ only on the row-blocks of $\Phi^{\mathcal{V}}$ corresponding to the incomplete prime components of G . Another possible strategy is that of exploiting (9) to independently compute the normalising constants for each marginal distribution corresponding to every incomplete prime component P with respect to $G_P = (P, \mathcal{P})$ and to chose $G_P^* = (P, \mathcal{P}^*)$ such that $|\mathcal{P}^*\setminus\mathcal{P}|$ is minimized; for a discussion on the triangulation of G_P see Cowell *et al.* (1999, p.57). In model search, this has the advantage that incomplete prime components common to different graphs need to be considered only once.

The second modification of the basic algorithm concerns the diagonal of $\Phi^{\mathcal{V}}$. The conditioning step of the R-C procedure leaves the distribution of the diagonal of $\Phi^{\mathcal{V}}$ identical to that of $\Phi^{\mathcal{V}^*}$. This is clearly a drawback, so that we introduce the following diagonal correction that, in the simulations we carried out, led to a substantial efficiency improvement.

- 4b. Correct the degrees of freedom of the chi-squared random variables on the main diagonal of $\Phi^{\mathcal{V}}$ by computing the indexes ν_i with respect to G rather than G^* .

We close this section with a remark concerning the hyperparameter space of the hyper inverse Wishart distribution. In the decomposable case the normalising constant $h_G(\delta)$ is finite for all $\delta > 0$ but, for arbitrary graph $G = (V, \mathcal{V})$, the hyperparameter space $H(G) = \{(\delta, D^{\mathcal{V}}) | \delta > 0, D^{\mathcal{V}} \in M_*^+(G), h_G(\delta, D^{\mathcal{V}}) < \infty\}$ has not been

fully identified. Bjerg and Nielsen (1993, p.87) provided a partial result by showing that $H(G)$ is a convex set. Furthermore, they noticed that a general result for the regular exponential family (Diaconis and Ylvisaker, 1979, Theorem 1) implies that $(2, +\infty) \times M_*^+(G) \subseteq H(G)$. Hence, in our applications we always set $\delta > 2$.

5.2 Simulations

The performance of the proposed importance sampler is illustrated here with respect to the two graphs in Figure 2. They are both incomplete prime graphs and the associated hyper inverse Wishart distributions have dimension 16 for graph (a) and 13 for graph (b). Figure 2 also shows the fill-in decomposable graphs G^* used in the R-C procedures.

Figure 2 about here

The estimated constants are compared with the asymptotic approximation based on Laplace's formulae (see Tierney and Kadane, 1986),

$$\tilde{h}_G(\delta, D^\nu) = \exp \left\{ -\frac{1}{2} \left[|\mathcal{V}| \log(2\pi\delta') + |V| \{ \delta' \log(\delta') + \log(2) - \delta' \} \right] \right\} \quad (10)$$

where $\delta' = \delta - 2$. Note that (10) is not a function of D^ν and depends on G only through $|V|$ and $|\mathcal{V}|$.

Tables 3 and 4 give the estimated $\log\{h_G(\delta, D^\nu)\}$ for different values of the hyperparameters δ and D^ν . As mentioned above, these tables provide an empirical evidence that, as well as for the decomposable case, also when G is non-decomposable the normalising constant does not depend on D^ν .

Tables 3 and 4 about here

Figure 3 describes the evolution of the estimators of $\log\{h_G(3, I)\}$ as the sample size increases. These examples show that our importance sampler works extremely well. For all the simulations the sample size was set to 15000; nevertheless, for a satisfactory estimate of the constant a much smaller number of iterations seems to suffice. Furthermore, we observed that the convergence rate improves as δ increases.

Figure 3 about here

All the computations were done on a Pentium II-266 using the interpreted language *R*. It is remarkable that, despite the lack of efficiency of such a language, the CPU time required by the procedure was always acceptable.

6 Data distribution and examples

We now apply the results of this paper to the analysis of the data in Tables 1 and 2.

The hyper inverse Wishart distribution is conjugate for the model and, for $G = (V, \mathcal{V})$, if the prior distribution of Σ^ν is $HIW_G(\delta, D^\nu)$ and a random sample X of size

n has been observed then the posterior is $HIW_G(\delta + n, (D + S)^\nu)$, where $S = n\hat{\Sigma}$. For G decomposable, the density of the marginal distribution of the data was given by Dawid and Lauritzen, (1993, equation (45)) and, by using (8) this can be generalised to the non-decomposable case as

$$u(x|G) = (2\pi)^{-np/2} \frac{h_G(\delta, D^\nu) |\text{Iss}(D)_{\nu\nu}|^{\frac{1}{2}} |D|^{(\delta-2)/2}}{h_G\{\delta + n, (D + S)^\nu\} |\text{Iss}(D + S)_{\nu\nu}|^{\frac{1}{2}} |(D + S)|^{(\delta+n-2)/2}} \quad (11)$$

where D and $(D + S)$ are the PD -completions of D^ν and $(D + S)^\nu$ respectively.

Both Tables 1 and 2 involve four variables. The set of all models for 4 variables is made up of 64 elements $\{G_{1,2}, \dots, G_{64}\}$, three of which non-decomposable. Here we use the marginal likelihood $\tilde{L}(G_i) = u(x|G_i)$ to derive the posterior distribution $\Pr(G_i|x)$ as well as to compute the Bayes factor $\Lambda(G_i, G_j) = \tilde{L}(G_i)/\tilde{L}(G_j)$ between competing models G_i and G_j .

For our analysis we assumed the prior distribution for the models to be constant, $\Pr(G_i) = 64^{-1}$ for $i = 1, \dots, 64$, so that $\Pr(G_i|x) \propto \tilde{L}(G_i)$. For either set of data, as hyperparameters of the prior distribution for Σ^ν we set $D = I$ and $\delta = 3$.

For the data in Table 1, Figure 4 shows the four models with the highest posterior probabilities. As expected, the graph of to the most probable model is a chordless four-cycle. Of main interest, however, is the strength with which this model is supported by the data: the Bayes factor against any of the remaining models is larger than 500. It is worth noticing that a model search restricted to the subset of decomposable models would have missed this important relation.

Figure 4 about here

Also for the Fisher's iris data the model with highest posterior probability is non-decomposable. In this case, however, several models have rather close posterior probabilities. In Figure 5 we give the sixteen most probable models; they represent the 25% of all possible models and the sum of their probabilities is 0.987. Note that also model number 11 is non-decomposable.

Figure 5 about here

7 Discussion

The main contribution of this paper concerns two distributions: the generalisation of the hyper inverse Wishart and the importance sampler. Nevertheless, it is worth pointing out the importance of the theory of T -completion for the development of all the material here presented. In fact, we deem that it might provide a tool with more general applications in the theory of non-decomposable Gaussian graphical models.

We conclude by noting that the assumption, here empirically proved, that $h_G(\delta, D^\nu)$ is not a function of D substantially reduce the number of constants to be numerically evaluated in a model search procedure. For example, in the application in Section 6 the three non-decomposable models on four variables are all chordless cycles so

that, given δ , $h_G(\cdot)$ has the same value for all of them. An analysis of all models for five variables would just require the evaluation of the constant for five graphs: the chordless four-cycle plus four prime graphs on five vertices.

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Appendix

A Cholesky decomposition of a concentration matrix

In stochastic simulation, when a positive definite matrix K has to be generated the Cholesky decomposition $K = \Phi^\top \Phi$ is widely used because the elements of Φ are variation independent. However, the variation independence property is not retained when, for an undirected graph $G = (V, \mathcal{V})$, K is restricted to belong to $M^+(G)$. Here we consider $K \in M^+(G)$ and partition Φ into $(\Phi^\mathcal{V}, \Phi^{\bar{\mathcal{V}}})$ so that Φ is the T -completion of $\Phi^\mathcal{V}$, defined in Section 2.2. In our approach, we assume that the elements of $\Phi^\mathcal{V}$, hereafter referred to as the free entries of Φ , are variation independent, $\Phi^\mathcal{V} \in M_*^s(G)$, and show that the fixed entries $\Phi^{\bar{\mathcal{V}}}$ of Φ are uniquely identified by the constraint $\Phi^\top \Phi \in M^+(G)$. As a consequence, the transformation $\Phi^\mathcal{V} \rightarrow K$, i.e. the transformation between the free entries of Φ and the nonzero entries of $K = \Phi^\top \Phi$, defines a bijective mapping between $M_*^s(G)$ and $M^+(G)$. The material presented in this appendix is concerned with this transformation and is mainly technical. We show how the T -completion of $\Phi^\mathcal{V}$ can be used to deal efficiently with the parameter space of an arbitrary Gaussian graphical model, describe the local computation property of T -completion operations and finally, provide the Jacobian of the inverse transformation $K \rightarrow \Phi^\mathcal{V}$.

We first describe the procedure for computing the T -completion Φ from the incomplete matrix $\Phi^\mathcal{V} \in M^+(G)$, where $G = (V, \mathcal{V})$ is an arbitrary undirected graph. In this way the existence and uniqueness of Φ are also shown.

Assume first $\Phi \in M^s$ and let $K = \Phi^\top \Phi$. Because of the triangular form of Φ , for any $(r, s) \in \mathcal{W}$

$$\kappa_{rs} = \sum_{i=1}^r \phi_{ir} \phi_{is}, \quad (\text{A1})$$

so that κ_{rs} is not a function of any ϕ_{ij} with either $i > r$ or $j > s$ and we can write

$$\kappa_{rs} = \kappa_{rs}(\Phi_{\{r\}\{s\}}), \quad (\text{A2})$$

where we recall that $\Phi_{\{r\}\{s\}} = \Phi_{\{1, \dots, r\}\{1, \dots, s\}}$.

Consider now $\Phi^\nu \in M_*^s(G)$ and let $(r, s) \in \bar{V}$, so that ϕ_{rs} is one of the specified entries of Φ^ν ; i.e. one of the fixed entries of Φ to be identified under the constraint $\Phi^\top \Phi = K \in M^+(G)$. Since in this case $\kappa_{rs} = 0$, by (A1) we have

$$\phi_{rs} = \begin{cases} 0 & \text{for } r = 1 \\ -\frac{1}{\phi_{rr}} \sum_{i=1}^{r-1} \phi_{ir} \phi_{is} & \text{for } r > 1. \end{cases} \quad (\text{A3})$$

In (A3), ϕ_{rs} is written as a function of both the free elements $\Phi_{\{r\}\{s\}}^\nu$ and the fixed elements $\Phi_{\{r-1\}\{s\}}^\nu$. Hence, if we order the specified entries of Φ^ν according to the rows of Φ^ν , then ϕ_{rs} is not a function of any of the other fixed elements following it in this sequence. Consequently, by following this ordering, (A3) can be used to recursively compute the T -completion of Φ^ν . More precisely, the fixed elements ϕ_{rs} with $r = 1$ are all zero and occupy the very first positions in the sequence. Thus, the first element of the sequence with $r > 1$, say ϕ_{rs} , is a function of $\Phi_{\{r\}\{s\}}^\nu$. Such a function, $\phi_{rs} = \phi_{rs}(\Phi_{\{r\}\{s\}}^\nu)$, is well defined because $\phi_{rr} > 0$ for all $\Phi^\nu \in M_*^s(G)$. Similarly, the next element of the sequence, say ϕ_{ij} , is a well defined function possibly involving $\phi_{rs}(\Phi_{\{r\}\{s\}}^\nu)$, of $\Phi_{\{i\}\{j\}}^\nu$, and so on. We can conclude that every fixed element ϕ_{rs} is uniquely identified as a function of $\Phi_{\{r\}\{s\}}^\nu$ so that

$$\Phi_{\{r\}\{s\}} = \Phi_{\{r\}\{s\}}(\Phi_{\{r\}\{s\}}^\nu) \quad (\text{A4})$$

is a one-to-one function available in closed form and, for $r = s = p$

$$\Phi = \Phi(\Phi^\nu) \quad (\text{A5})$$

is well defined for all $\Phi^\nu \in M_*^s(G)$ and identifies the unique T -completion of Φ^ν .

Example 5. For the graph G in Figure 1, the T -completion of $\Phi^\nu \in M_*^s(G)$ is

$$\Phi(\Phi^\nu) = \begin{pmatrix} \phi_{11} & \phi_{12} & 0 & \phi_{14} \\ 0 & \phi_{22} & \phi_{23} & -\frac{\phi_{12}\phi_{14}}{\phi_{22}} \\ 0 & 0 & \phi_{33} & \phi_{34} \\ 0 & 0 & 0 & \phi_{44} \end{pmatrix}.$$

□

The procedure $\Phi^\nu \rightarrow \Phi(\Phi^\nu) \rightarrow \Phi^\top \Phi$ provides an efficient way for generating elements from the set $M^+(G)$: an incomplete matrix Φ^ν can be easily constructed since its elements are variation independent and the recursive computation of $\Phi(\Phi^\nu)$ is efficient because the elements in the same row of Φ^ν can be computed in parallel. It should also be noticed that the determinant of K can be directly computed from Φ^ν , $|K| = \prod_{r=1}^p \phi_{rr}^2$, and the trace from Φ , $\text{tr}(K) = \sum_{r=1}^p \sum_{s=r}^p \phi_{rs}^2$.

Given $K \in M^+(G)$ the matrix Φ defined by $K = \Phi^\top \Phi$ is uniquely identified. Nevertheless, it depends on the permutation of the indices V ; that is on the permutation of the rows and columns of K . This has also an influence on the functional form

of (A5) and a different vertex ordering may bring to an efficiency improvement in its computation. Wermuth (1980) showed that when G is decomposable, taking a vertex ordering that follows a perfect vertex elimination scheme for G implies $\Phi^{\bar{\mathcal{V}}} = 0$ for all $K \in M^+(G)$. She also showed that this cannot be generalised to non-decomposable graphs (see also Paulsen *et al.*, 1989 and Roverato, 2000). Nevertheless, Wermuth's (1980) result can be exploited to show the following.

Proposition 1 *For $G = (V, \mathcal{V})$ let Φ be the T -completion of $\Phi^{\mathcal{V}} \in M_*^{\mathfrak{a}}(G)$. If $G^* = (V, \mathcal{V}^*)$ is a decomposable graph with $\mathcal{V} \subseteq \mathcal{V}^*$ and such that the vertices V are enumerated along a perfect sequence of prime components of G^* , then $\Phi^{\bar{\mathcal{V}}^*} = 0$.*

Proof. Wermuth (1980) showed that $\Phi^{\bar{\mathcal{V}}^*} = 0$ for all Φ such that $\Phi^{\top} \Phi \in M^+(G^*)$ and the result follows because $M^+(G) \subseteq M^+(G^*)$. \square

An important property for the analysis of graphical models is that of model collapsibility (Asmussen and Edwards, 1983; Wermuth, 1989). It is strictly related with the collapsibility of G and allows to compute several statistical quantities locally on marginal models. We show now that the T -completion of $\Phi^{\mathcal{V}}$ only requires to consider the incomplete prime components of G and that these can be computed locally and in parallel.

We first show that collapsibility of G implies that T -completion can be performed locally on different row-blocks of the incomplete matrix.

Proposition 2 *For $G = (V, \mathcal{V})$ let Φ be the T -completion of $\Phi^{\mathcal{V}} \in M_*^{\mathfrak{a}}(G)$. If G is collapsible onto $B = \{b, b+1, \dots, p\}$ and $A = V \setminus B$, then*

- (i) Φ_{AV} is a one-to-one function of $\Phi_{AV}^{\mathcal{V}}$;
- (ii) Φ_{BB} is the T -completion of $\Phi_{BB}^{\mathcal{V}} = \Phi_{BB}^{\mathfrak{B}}$ with respect to G_B .

Proof. (i) is always true. In fact, by putting $a = b - 1$ we can write $\Phi_{AV} = \Phi_{\{a\}\{p\}}$ so that by (A4) $\Phi_{\{a\}\{p\}} = \Phi_{\{a\}\{p\}}(\Phi_{\{a\}\{p\}}^{\mathcal{V}})$ is a one-to-one function. We now show (ii). It is always true that $\Phi_{BB}^{\mathcal{V}} = \Phi_{BB}^{\mathfrak{B}} \in M^{\mathfrak{a}}(G_B)$. If G is collapsible onto B then $K_{BB|A} \in M^+(G_B)$ and the result follows because $K_{BB|A} = \Phi_{BB}^{\top} \Phi_{BB}$; see also (A10) below. \square

Considerer now $\Phi^{\mathcal{V}} \in M_*^{\mathfrak{a}}(G)$ where $G = (V, \mathcal{V})$ is an arbitrary undirected graph such that the vertices V are ordered along a perfect sequence (P_1, \dots, P_k) of prime components of G . In this case the decomposable fill-in augmented graph $G^* = (V, \mathcal{V}^*)$ obtained by completing the prime components of G , that is $(r, s) \in \mathcal{V}^*$ if either $(r, s) \in \mathcal{V}$ or $\{r, s\} \in P_j$ for some $j = 1, \dots, k$, satisfies the conditions of Proposition 1. Hence, the T -completion Φ of $\Phi^{\mathcal{V}}$ can be partitioned into $(\Phi^{\mathcal{V}^*}, \Phi^{\bar{\mathcal{V}}^*})$ which $\Phi^{\mathcal{V}^*} = 0$ whereas $\Phi^{\bar{\mathcal{V}}^*}$ is made up of the row-blocks

$$\Phi_{P_1 P_1}, \quad (\Phi_{R_2 R_2} \Phi_{R_2 S_2}), \dots, (\Phi_{R_k R_k} \Phi_{R_k S_k}). \quad (\text{A6})$$

It follows that, in order to obtain the T -completion of $\Phi^\mathcal{V}$ it is sufficient to derive the unspecified entries of the submatrices

$$\Phi_{P_1 P_1}^{\mathcal{P}_1} \quad \text{and, for } j = 2, \dots, k, \quad \Phi_{P_j P_j}^{\mathcal{P}_j} = \begin{pmatrix} \Phi_{R_j R_j} & \Phi_{R_j S_j} \\ 0 & \Phi_{S_j S_j} \end{pmatrix}^{\mathcal{P}_j} \quad (\text{A7})$$

which are incomplete only if the corresponding prime components are incomplete. It can also be checked that, because of the zero structure of Φ ,

$$\Phi_{P_1 P_1}^\top \Phi_{P_1 P_1} = \Sigma_{P_1 P_1}^{-1} \quad (\text{A8})$$

and, for $j = 2, \dots, k$,

$$\begin{pmatrix} \Phi_{R_j R_j}^\top & 0 \\ \Phi_{S_j R_j} & \cdot \end{pmatrix} \begin{pmatrix} \Phi_{R_j R_j} & \Phi_{R_j S_j} \\ 0 & \cdot \end{pmatrix} = \Sigma_{P_j P_j}^{-1} \quad (\text{A9})$$

where dots denote submatrices which need not to be specified explicitly (see also Roverato, 2000, equations (14) and (15)). We can now give the main result of this appendix.

Theorem 1 *For $G = (V, \mathcal{V})$ let Φ be the T -completion of $\Phi^\mathcal{V} \in M_*^\triangleleft(G)$. If the vertices V are enumerated along a perfect sequence of prime components (P_1, \dots, P_k) of G , then for every incomplete prime component P_j of G , the submatrix $\Phi_{P_j P_j}$ of Φ is the T -completion of $\Phi_{P_j P_j}^{\mathcal{P}_j}$ with respect to G_{P_j} . All the remaining unspecified elements of $\Phi^\mathcal{V}$ are zero.*

Proof. We have shown above that under the conditions of the theorem, the T -completion of $\Phi^\mathcal{V}$ only requires to consider the unspecified entries of the submatrices $\Phi_{P_j P_j}^{\mathcal{P}_j}$ where P_j is an incomplete prime component of G . Thus, we have to show that the submatrix $\Phi_{P_j P_j}$ of Φ is the T -completion of $\Phi_{P_j P_j}^{\mathcal{P}_j} \in M(G_{P_j})$ for $j = 1, \dots, k$.

Consider first $j = k$. Since $G_{H_k} = G$ is collapsible onto $G_{H_{k-1}}$, we can apply Proposition 2 with $A = R_k$ and $B = H_{k-1}$ to obtain that $(\Phi_{R_k R_k} \Phi_{R_k S_k})$ is a one-to-one function of $(\Phi_{R_k R_k} \Phi_{R_k S_k})^{\mathcal{P}_k}$. If P_k is complete such a function is trivial, otherwise it is given by (A4) and, since S_k is complete, by (A7) is the T -completion of $\Phi_{P_k P_k}^{\mathcal{P}_k}$. By Proposition 2, $\Phi_{H_{k-1} H_{k-1}}$ is the T -completion of $\Phi_{H_{k-1} H_{k-1}}^{\mathcal{H}_{k-1}} \in M(G_{H_{k-1}})$ and the result for $j = 1, \dots, k-1$ follows by recursive application of the the same procedure. \square

Throughout this paper $K = \Sigma^{-1}$ is the canonical parameter of $X_V \sim N(0, \Sigma)$. The following statistical interpretation of Φ was given by Wermuth (1980); see also Massam and Neher (1997) and Roverato, (2000).

Assume $B = \{b, b+1, \dots, p\}$ and let $A = V \setminus B$ so that the pair (A, B) is a partition of V . The triangular matrix Φ can be partitioned accordingly

$$K = \begin{pmatrix} \Phi_{AA}^\top & 0 \\ \Phi_{BA} & \Phi_{BB}^\top \end{pmatrix} \begin{pmatrix} \Phi_{AA} & \Phi_{AB} \\ 0 & \Phi_{BB} \end{pmatrix}$$

and, by applying the rules for the inverse of a partitioned matrix it is straightforward to check that the two row-blocks $\Phi_{AV} = (\Phi_{AA}, \Phi_{AB})$ and Φ_{BB} are one-to-one functions of the parameters $(\Gamma_{A|B}, \Sigma_{AA|B})$ and Σ_{BB} of $X_A|X_B$ and X_B respectively

$$\begin{aligned}\Phi_{AA}^\top \Phi_{AA} &= (\Sigma_{AA|B})^{-1} \\ -\Phi_{AA}^{-1} \Phi_{AB} &= \Gamma_{A|B} \\ \Phi_{BB}^\top \Phi_{BB} &= \Sigma_{BB}^{-1}.\end{aligned}\tag{A10}$$

Hence a consequence of Proposition 2 is as follows.

Corollary 3 *If $G = (V, \mathcal{V})$ is collapsible onto $B = \{b, b+1, \dots, p\}$ and $\Phi^\top \Phi = \Sigma^{-1} \in M^+(G)$, then $(\Gamma_{A|B}, \Sigma_{AA|B})$ is a one-to-one function of $\Phi_{AV}^\mathcal{V}$ and Σ_{BB} is a one-to-one function of Φ_{BB}^B .*

We close this appendix by computing the Jacobian of the transformation $K \rightarrow \Phi^\mathcal{V}$ which is used both in the proof of Theorem 1 and in Section 5.

Proposition 3 *For $\Phi^\mathcal{V} \in M_*^s(G)$, where $G = (V, \mathcal{V})$, let $K = \Phi(\Phi^\mathcal{V})^\top \Phi(\Phi^\mathcal{V})$. The Jacobian of the inverse transformation $K \rightarrow \Phi^\mathcal{V}$ is*

$$J(K \rightarrow \Phi^\mathcal{V}) = 2^p \prod_{i=1}^p \phi_{ii}^{\nu_i+1}.$$

Proof. By applying (A4) to (A2) we obtain $\kappa_{rs} = \kappa_{rs}(\Phi_{\{r\}|\{s\}}^\mathcal{V})$, so that whenever either $i > r$ or $j > s$ we have $\frac{d}{d\phi_{ij}} \kappa_{rs} = 0$. Thus, if we take the distinct nonzero elements of K ordered according to the rows of K , and similarly for the elements of $\Phi^\mathcal{V}$, the Jacobian matrix $J = \frac{\partial}{\partial \Phi^\mathcal{V}} K$ is triangular and its determinant is the product of the diagonal elements

$$|J| = \prod_{(r,s) \in \mathcal{V}} \frac{d}{d\phi_{rs}} \kappa_{rs}.\tag{A11}$$

By (A1) for all $(r, s) \in \mathcal{V}$ we can write $\kappa_{rs} = \sum_{i=1}^{r-1} \phi_{ir} \phi_{is} + \phi_{rr} \phi_{rs}$ where, when $r = 1$ the expression involving $\sum_{i=1}^{r-1}$ must be considered zero. By (A4), none of the terms of the sum $\sum_{i=1}^{r-1} \phi_{ir} \phi_{is}$ is a function of ϕ_{rs} so that $\frac{d}{d\phi_{rs}} \kappa_{rs} = \frac{d}{d\phi_{rs}} \phi_{rr} \phi_{rs}$. For $r = s$ this derivative is $\frac{d}{d\phi_{rr}} \kappa_{rr} = 2\phi_{rr}$ while for $r < s$ with $(r, s) \in \mathcal{V}$ it is $\frac{d}{d\phi_{rs}} \kappa_{rs} = \phi_{rr}$. By noticing that such derivatives only depend on the row position of κ_{rs} , and the i th row of $\Phi^\mathcal{V}$ has exactly $\nu_i + 1$ specified elements, it follows that $|J| = 2^p \prod_{i=1}^p \phi_{ii}^{\nu_i+1}$ and the proof is complete. \square

B Proof of Lemma 1

(ii) and (iii) are equivalent because, by (A10), $K_{BB|A} = \Phi_{BB}^\top \Phi_{BB}$, $K_{AB} = \Phi_{AA}^\top \Phi_{AB}$ and $K_{AA} = \Phi_{AA}^\top \Phi_{AA}$. Hence, only (i) and (iii) need to be proved.

We first consider (iii). By Proposition 2, $(\Phi_{AA}, \Phi_{AB}) = \Phi_{AV}$ is independent of Φ_{BB} if and only if $\Phi_{AV}^\nu \perp\!\!\!\perp \Phi_{BB}^{\mathcal{B}}$. To prove the independence of Φ_{AV} and Φ_{BB} it is therefore sufficient to show that the density function of the distribution induced on Φ^ν by K factorises as

$$f(\Phi^\nu|\delta, T) = f_{AV}(\Phi_{AV}^\nu|\delta, T) \times f_{BB}(\Phi_{BB}^{\mathcal{B}}|\delta, T_{BB}) \quad (\text{B1})$$

where T is defined by $Q = T^\top T$.

The density function (B1) can be derived by replacing K by $\Phi^\top \Phi$ in (6) and multiplying it by the Jacobian in Proposition 3 and has form

$$f(\Phi^\nu|\delta, T) \propto \left(\prod_{r=1}^p \phi_{rr}^{\delta-2} \right) \exp \left[-\frac{1}{2} \text{tr} \left\{ \Phi^\top \Phi (T^\top T)^{-1} \right\} \right] \prod_{r=1}^p \phi_{rr}^{\nu_r+1}, \quad (\text{B2})$$

where T is defined by $Q = T^\top T$. Recall that $|K| = \prod_{r=1}^p \Phi_{rr}^2$.

Let $\text{SS}(M)$ denote the sum of squares of the entries of a matrix M so that if M is upper triangular $\text{SS}(M) = \text{tr}(M^\top M)$. By noticing that both T^{-1} and ΦT^{-1} are upper triangular and that $(\Phi T^{-1})_{AV} = \Phi_{AV} T^{-1}$ and $(\Phi T^{-1})_{BB} = \Phi_{BB} T_{BB}^{-1}$, we can write

$$\begin{aligned} \text{tr} \left\{ \Phi^\top \Phi (T^\top T)^{-1} \right\} &= \text{tr} \left(\Phi^\top \Phi T^{-1} T^{-\top} \right) \\ &= \text{tr} \left\{ (\Phi T^{-1})^\top (\Phi T^{-1}) \right\} \\ &= \text{SS}(\Phi T^{-1}) \\ &= \text{SS}\{(\Phi T^{-1})_{AV}\} + \text{SS}\{(\Phi T^{-1})_{BB}\} \\ &= \text{SS}(\Phi_{AV} T^{-1}) + \text{SS}(\Phi_{BB} T_{BB}^{-1}) \\ &= \text{SS}(\Phi_{AV} T^{-1}) + \text{tr} \left\{ (\Phi_{BB} T_{BB}^{-1})^\top (\Phi_{BB} T_{BB}^{-1}) \right\} \\ &= \text{SS}(\Phi_{AV} T^{-1}) + \text{tr} \left\{ \Phi_{BB}^\top \Phi_{BB} (T_{BB}^\top T_{BB})^{-1} \right\}. \end{aligned} \quad (\text{B3})$$

By using (B3) in (B2), $f(\Phi^\nu|\delta, T)$, can be factorised as in (B1) with

$$f_{AV}(\Phi_{AV}^\nu|\delta, T) \propto \left(\prod_{r=1}^{b-1} \phi_{rr}^{\delta-2} \right) \exp \left\{ -\frac{1}{2} \text{SS}(\Phi_{AV} T^{-1}) \right\} \prod_{r=1}^{b-1} \phi_{rr}^{\nu_r+1}$$

and

$$f_{BB}(\Phi_{BB}^{\mathcal{B}}|\delta, T_{BB}) \propto \left(\prod_{r=b}^p \phi_{rr}^{\delta-2} \right) \exp \left[-\frac{1}{2} \text{tr} \left\{ \Phi_{BB}^\top \Phi_{BB} (T_{BB}^\top T_{BB})^{-1} \right\} \right] \prod_{r=b}^p \phi_{rr}^{\nu_r+1} \quad (\text{B4})$$

where $\Phi_{AV} = \Phi_{AV}(\Phi_{AV}^\nu)$ and $\Phi_{BB} = \Phi_{BB}(\Phi_{BB}^{\mathcal{B}})$ by Proposition 2. We have thus shown the independence Φ_{AV} and Φ_{BB} .

Consider now (i). Because of the zero structure of K , the support of the distribution of $K_{BB|A}$ is $M^+(G_B)$ (Whittaker, 1990, p.397) whereas its density function can be derived by considering the transformation $K_{BB|A} = \Phi_{BB}(\Phi_{BB}^{\mathcal{B}})^\top \Phi_{BB}(\Phi_{BB}^{\mathcal{B}})$ where the distribution of $\Phi_{BB}^{\mathcal{B}}$ has density (B4). Since $\Phi_{BB}^\top \Phi_{BB} = K_{BB|A}$ and $T_{BB}^\top T_{BB} = Q_{BB|A}$,

we have that $\prod_{r=b}^p \phi_{rr}^{\delta-2} = |K_{BB|A}|^{(\delta-2)/2}$ and $\prod_{r=b}^p \phi_{rr}^{\nu_r+1} = J(K_{BB|A} \rightarrow \Phi_{BB}^B)$ by Proposition 3. Consequently the distribution of $K_{BB|A}$ has density

$$q_{G_B}(K_{BB|A}|\delta, Q_{BB|A}) \propto |K_{BB|A}|^{(\delta-2)/2} \exp\left[-\frac{1}{2} \text{tr}\{K_{BB|A}(Q_{BB|A})^{-1}\}\right] \quad (\text{B5})$$

and this establishes (i).

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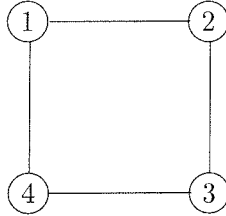


Figure 1: Chordless four-cycle.

Table 1: Summary statistics about four psychological variables for 684 students. Variances (main diagonal), covariances (lower triangle), partial correlations given the other two variables (upper triangle).

	S. anx	S. ang	T. anx	T. ang
State anxiety	37.21	0.45	0.47	-0.04
State anger	24.93	44.89	0.03	0.32
Trait anxiety	21.48	17.89	32.26	0.32
Trait anger	15.63	22.01	18.29	43.16

Table 2: *Fisher's iris data*. Summary statistics about four variables for 50 flowers from iris-Virginica species. Variances (main diagonal), covariances (lower triangle), partial correlations given the other two variables (upper triangle).

	SL	SW	PL	PW
Sepal length	0.396	0.269	0.838	-0.125
Sepal width	0.092	0.102	-0.076	0.484
Petal length	0.297	0.070	0.298	0.180
Petal width	0.048	0.047	0.048	0.074

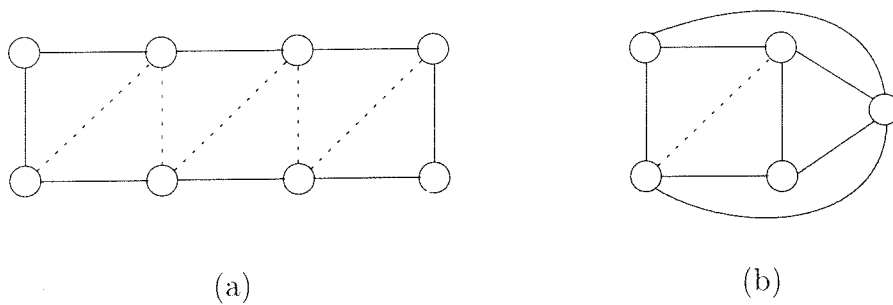


Figure 2: Non-decomposable graphs and their triangulations. Dashed lines: fill-in edges.

Table 3: Estimated $\log\{h_G(\delta, D^\nu)\}$ for the graph in Figure 2 (a) (16 parameters). LA: Laplace approximation. I : identity matrix. D_i for $i = 1, \dots, 4$: randomly chosen positive definite matrices.

	$\delta = 3$	$\delta = 5$	$\delta = 10$	$\delta = 20$	$\delta = 40$	$\delta = 60$
LA	-13.476	-27.448	-68.653	-176.70	-447.49	-759.98
I	-18.444	-29.530	-69.513	-177.10	-447.68	-760.11
D_1	-18.446	-29.529	-69.511	-177.10	-447.68	-760.11
D_2	-18.443	-29.531	-69.514	-177.10	-447.68	-760.11
D_3	-18.440	-29.533	-69.516	-177.10	-447.68	-760.11
D_4	-18.444	-29.535	-69.514	-177.10	-447.68	-760.11

Table 4: Estimated $\log\{h_G(\delta, D^\nu)\}$ for the graph in Figure 2 (b) (13 parameters). LA: Laplace approximation. I : identity matrix. D_i for $i = 1, \dots, 4$: randomly chosen positive definite matrices.

	$\delta = 3$	$\delta = 5$	$\delta = 10$	$\delta = 20$	$\delta = 40$	$\delta = 60$
LA	-11.179	-21.559	-48.784	-117.53	-287.89	-483.84
I	-16.360	-23.887	-49.783	-118.00	-288.12	-483.99
D_1	-16.372	-23.905	-49.793	-118.00	-288.12	-483.99
D_2	-16.397	-23.897	-49.804	-118.01	-288.12	-483.99
D_3	-16.387	-23.915	-49.794	-118.01	-288.12	-483.99
D_4	-16.371	-23.892	-49.801	-118.01	-288.12	-483.99

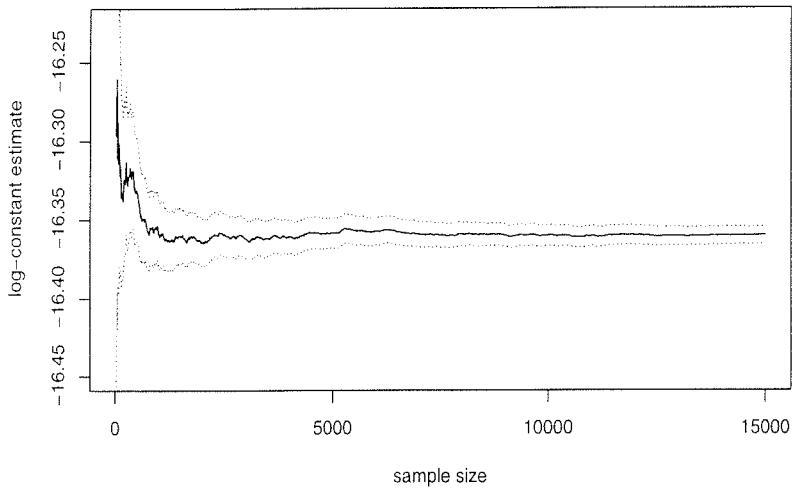
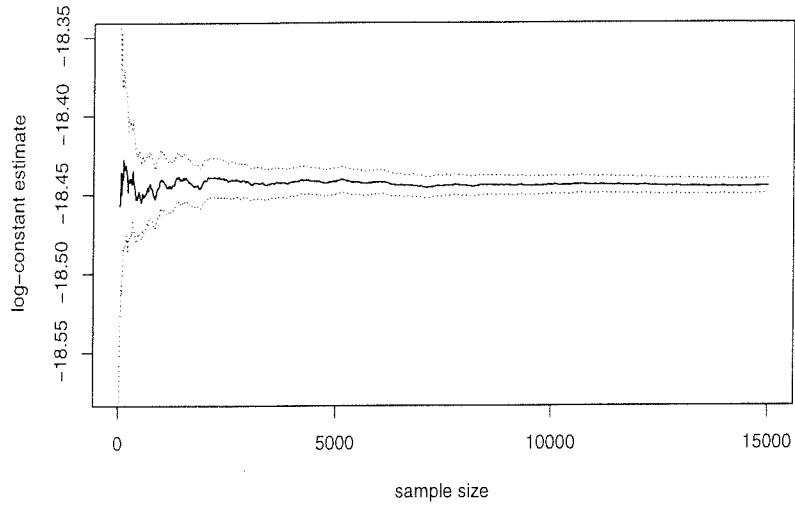


Figure 3: Convergence of the estimator of $\log\{h_G(3, I)\}$ for the graphs in Figure 2 (a) and (b). The envelope provides a 95% Monte Carlo confidence interval.

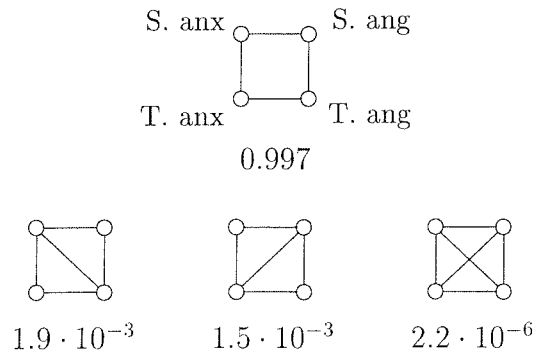


Figure 4: Data in Table 1: Four most probable models.

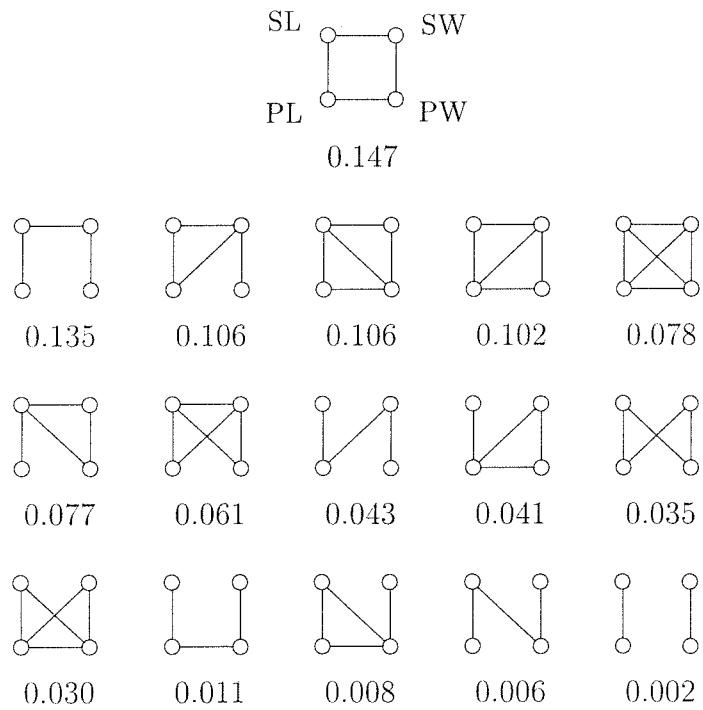


Figure 5: Fisher's iris data: Sixteen most probable models.

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